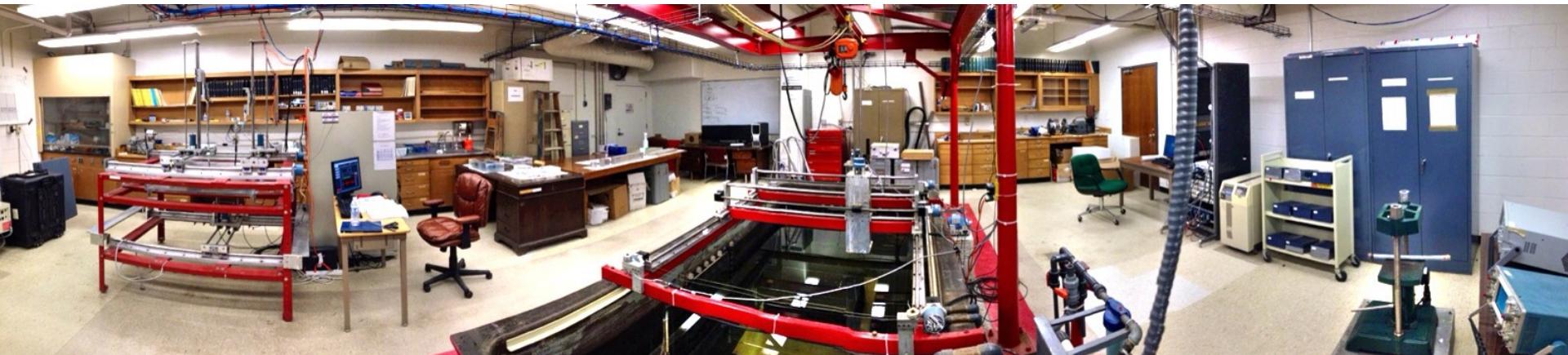


# Guided waves in shallow water: A physical modeling study



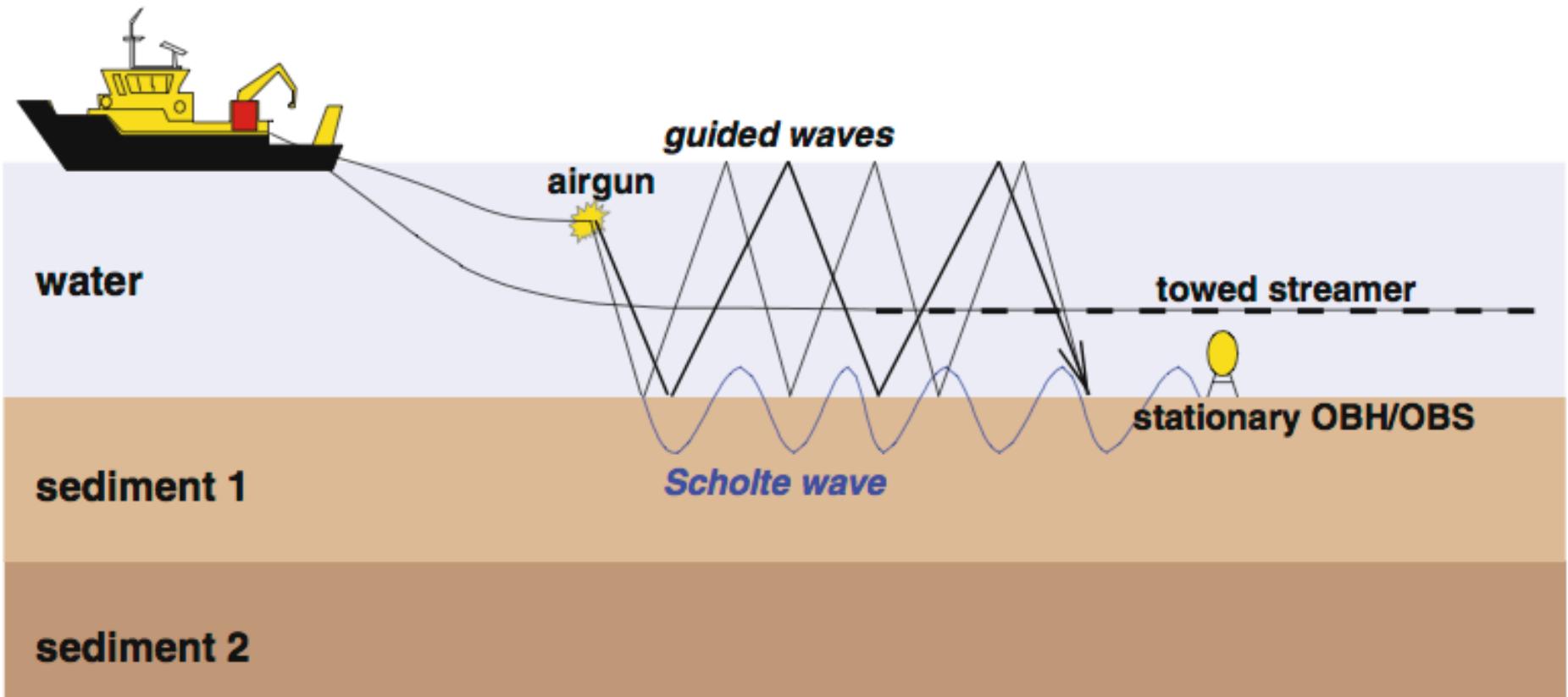
Jiannan Wang

May 2013  
Department of Earth & Atmospheric Sciences  
University of Houston

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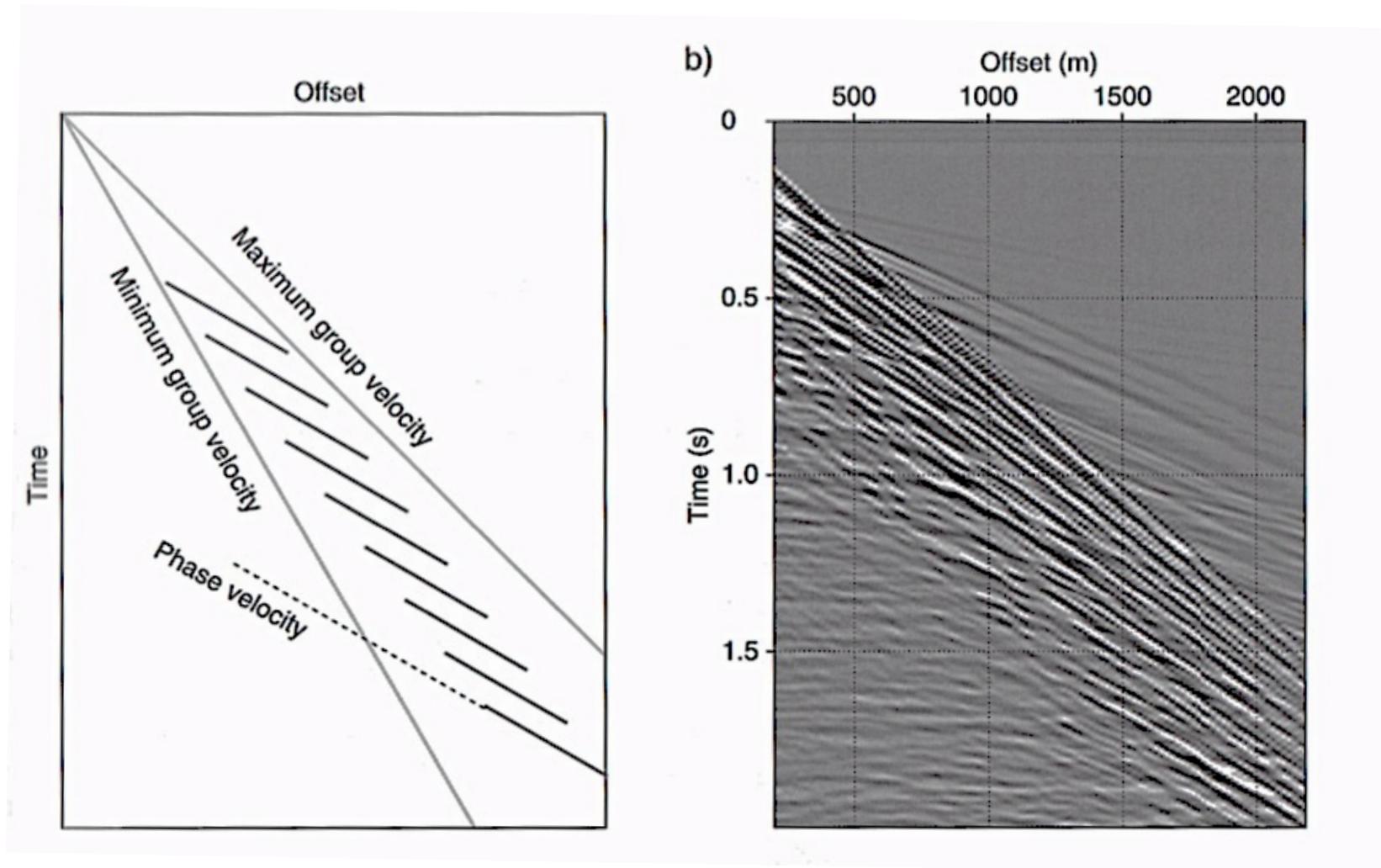
- Dispersion features of guided water waves
- Physical modeling
  - Different water depths;
  - Different seafloor dipping angles;
  - Different thicknesses of the sedimentary layer;
- Applications
  - Sub-bottom Vs profile building and filter design
- Conclusions
  - Major effects from geometrical scenarios
  - Necessary of filter design

# Marine seismic guided and interface waves



(Klein, 2004)

# Dispersion features in shot gather



(Liner, DISC 2012)

# Wavefield Solution

General form:

$$\phi = \int F(k) dk + \sum residues$$



**continuous spectrum**

**diminish as  $1/r^2$**



**discrete spectrum**

**diminish as  $1/r^{1/2}$**

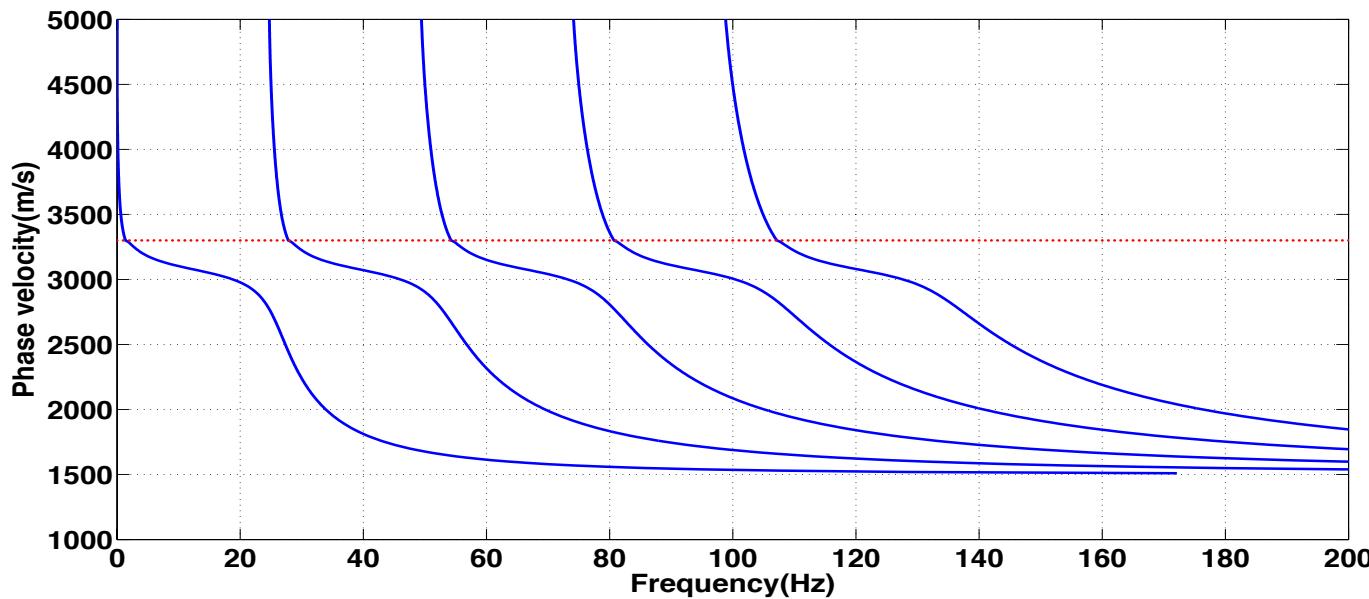
(Pekeris, 1948)

Dispersion equation:

$$\tan \left[ \frac{2\pi f}{c_n} H \sqrt{c_n^2/\alpha_1^2 - 1} - \left( n - \frac{1}{2} \right) \pi \right] = \frac{\rho_2}{\rho_1} \frac{\beta_2^4}{c_n^4} \frac{\sqrt{c_n^2/\alpha_1^2 - 1}}{\sqrt{1 - c_n^2/\alpha_2^2}} \left[ 4 \sqrt{1 - c_n^2/\alpha_2^2} \sqrt{1 - c_n^2/\beta_2^2} - (2 - c_n^2/\beta_2^2)^2 \right]$$

(Press, 1949)

$f$  is the frequency;  $c_n$  is the phase velocity;  $n$  is the mode number;  $\alpha_1$ ,  $\alpha_2$  is the P-wave velocity of water and seafloor, respectively;  $\beta_2$  is the shear-wave velocity of seafloor;  $\rho_1$  and  $\rho_2$  is the density of water and seafloor, respectively.



$V=1500 \text{ m/s},$   
 $\rho=1 \text{ g/cm}^3$

$V_p=6300 \text{ m/s}$   $V_s=$   
 $3300 \text{ m/s}$   
 $\rho=2.7 \text{ g/cm}^3$

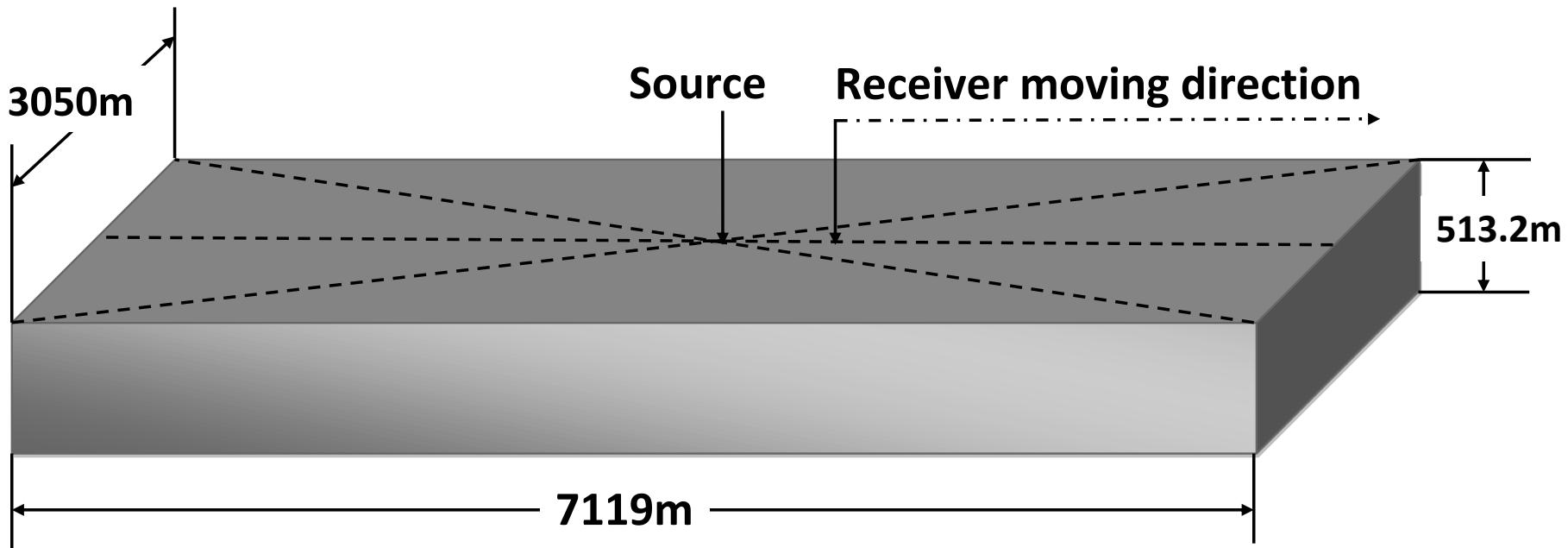
# Hard Seafloor: Aluminum Block

Aluminum Block:

$$Vp = 6300 \text{ m/s}, Vs = 3300 \text{ m/s}, \rho = 2.7 \text{ g/cm}^3$$

Basalt:

$$Vp = 6300 \text{ m/s}, Vs = 3200 \text{ m/s}, \rho = 2.4 \text{ g/cm}^3$$

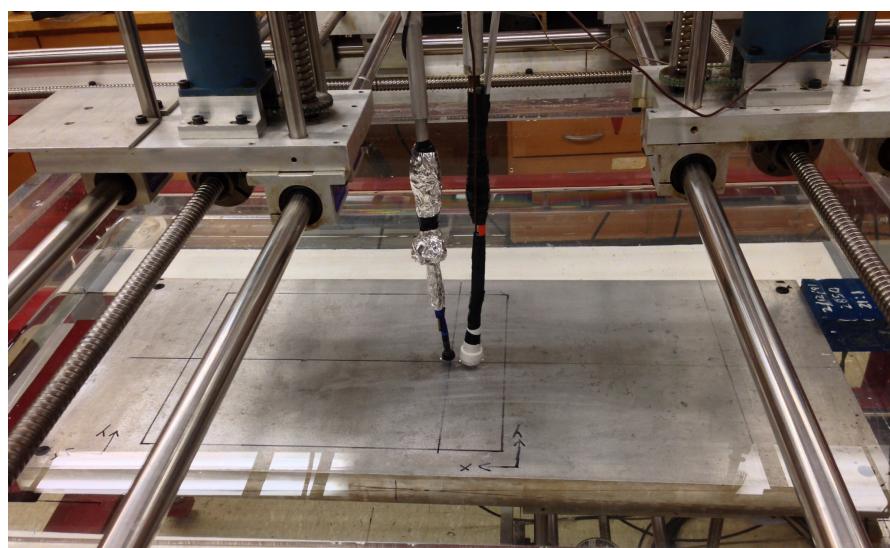
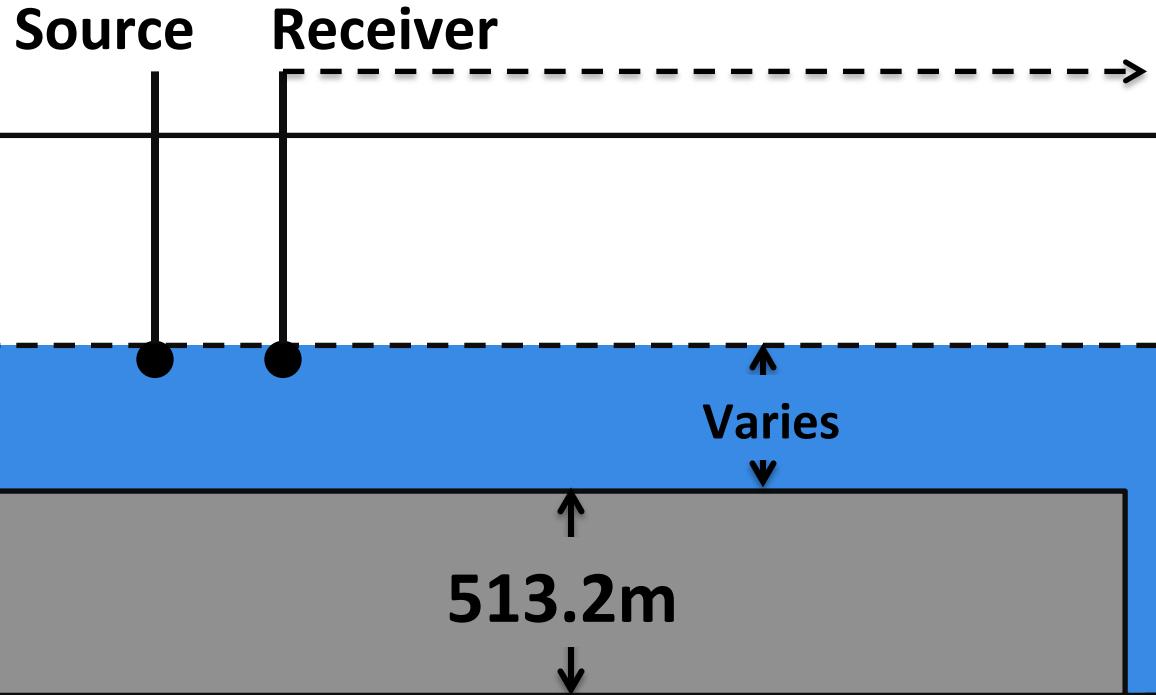


## Geometry:

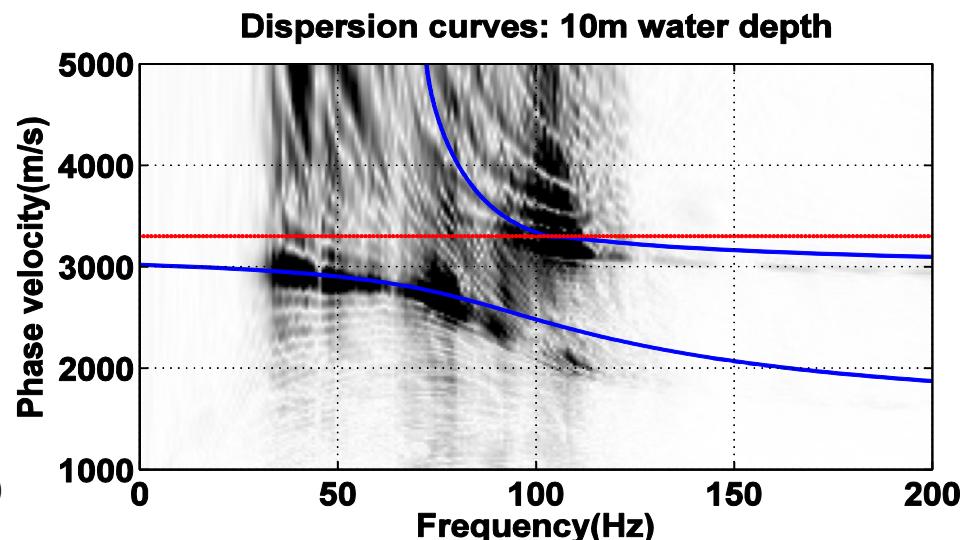
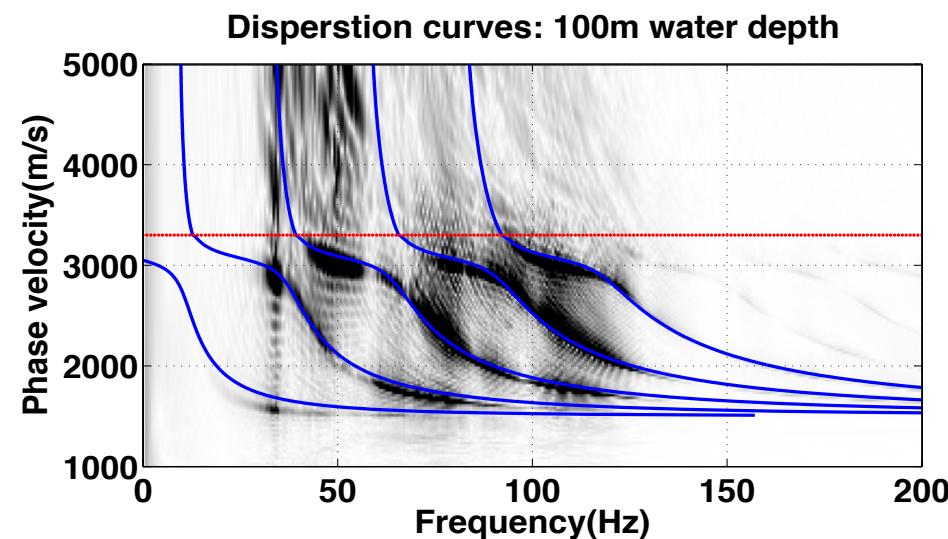
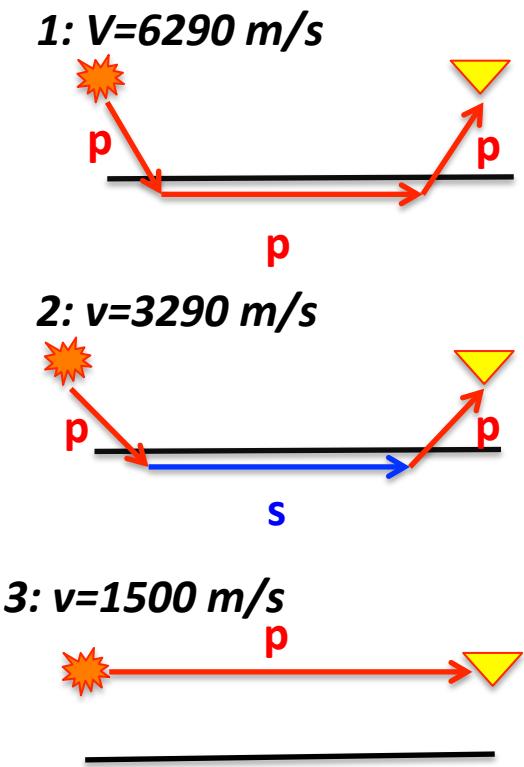
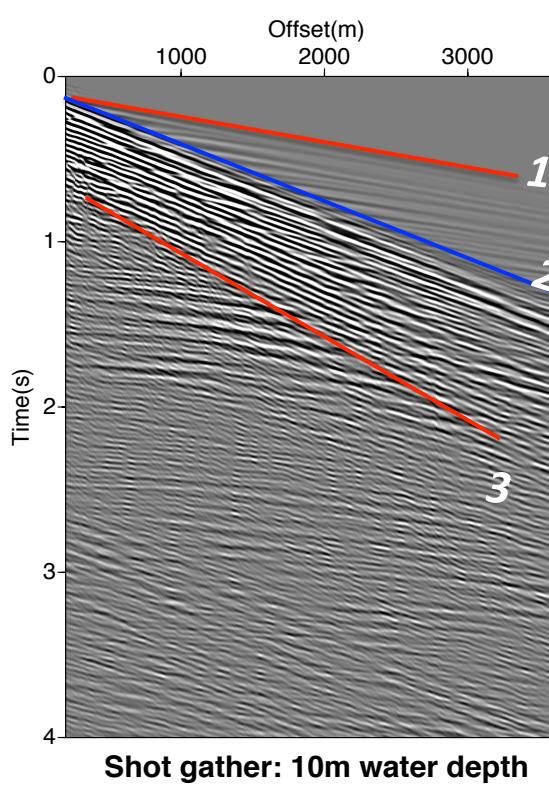
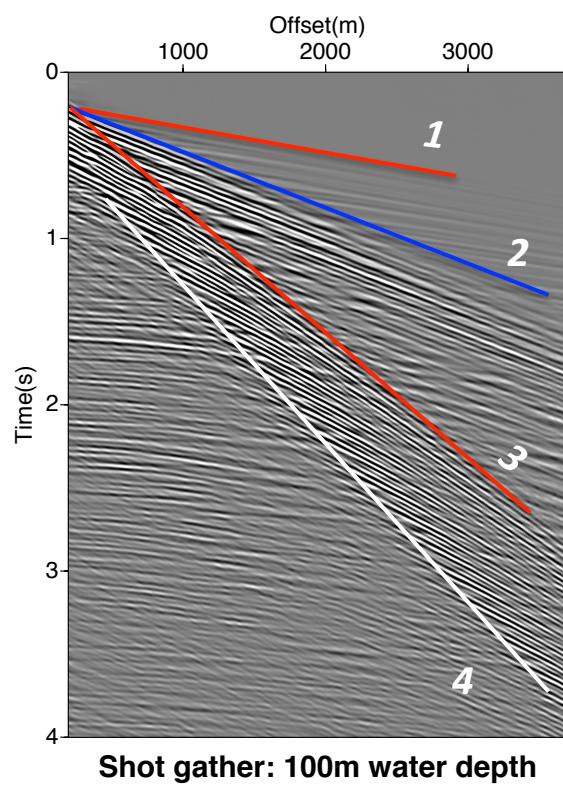
- Offset Range: 200~3500 m (2cm ~35cm);
- Near offset: 200 m (2cm);
- Far offset: 3500 m (35cm);

- Receiver interval: 10m(1mm);
- Central frequency: 30Hz.
- Scale factor:  $10^4$ .

# Varying depth

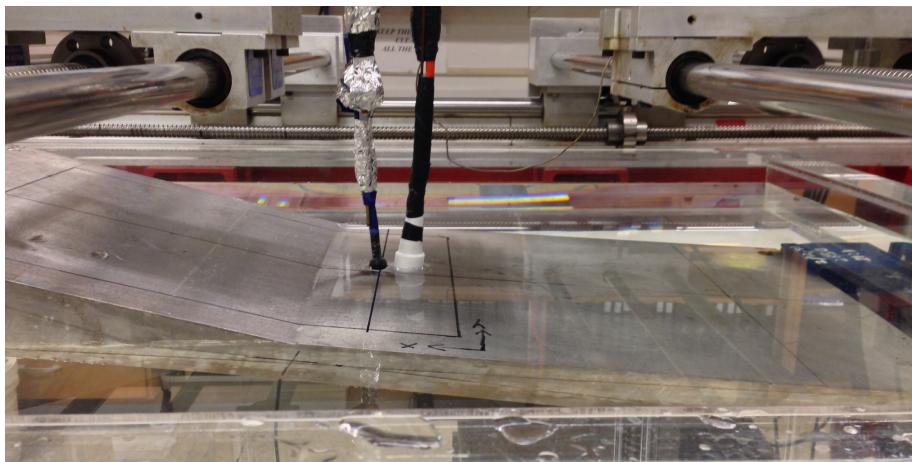
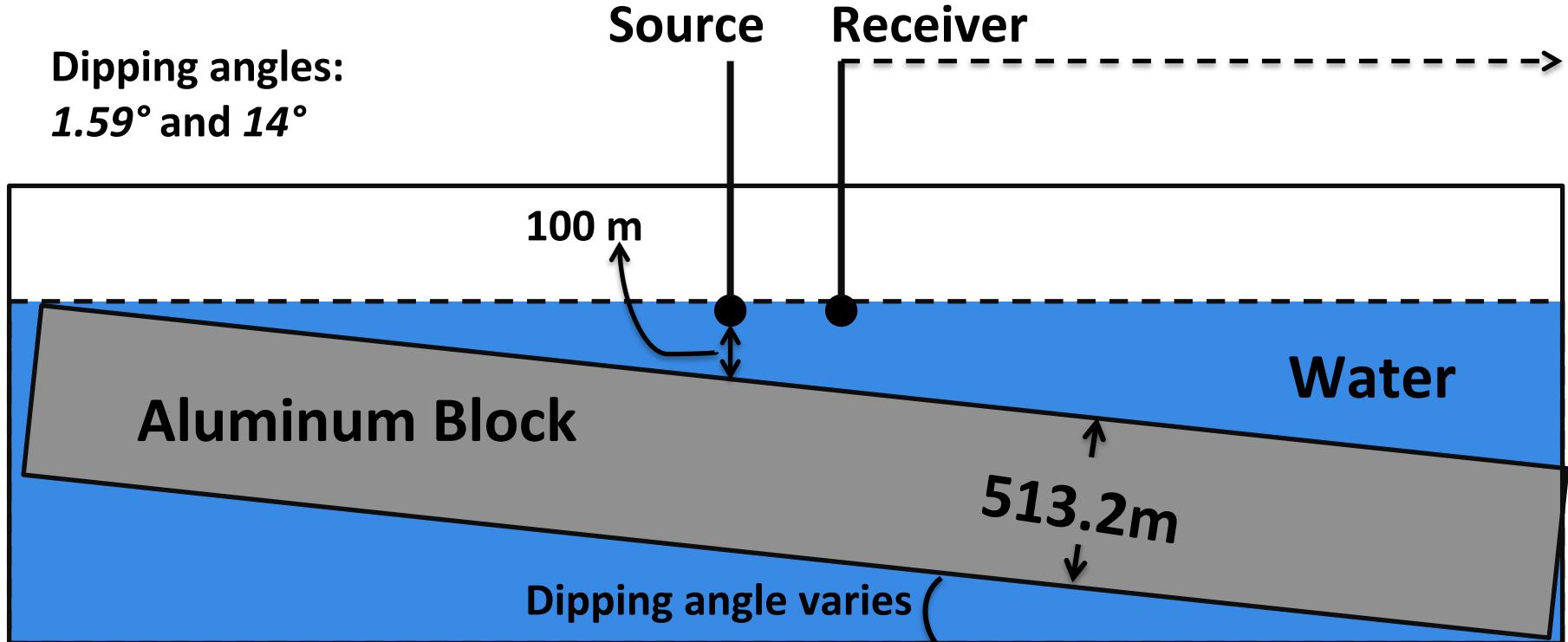


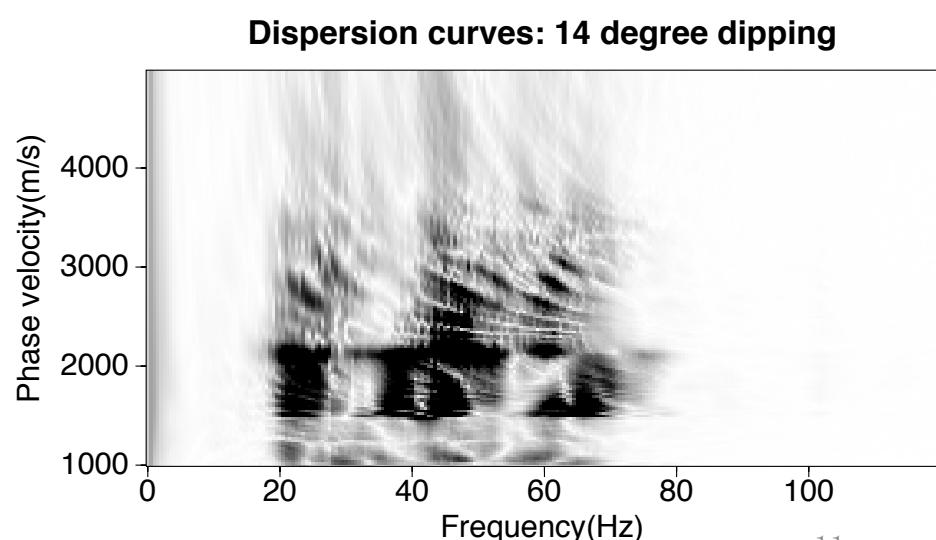
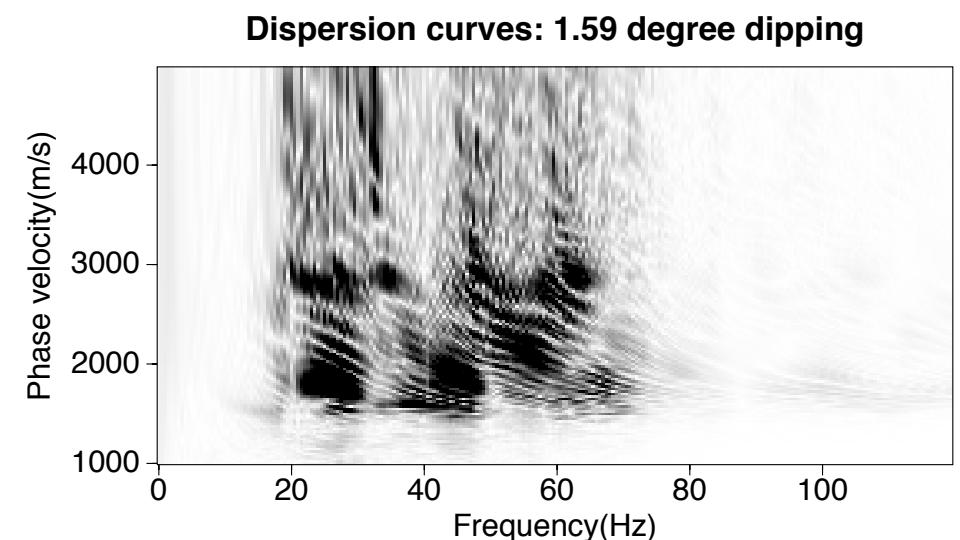
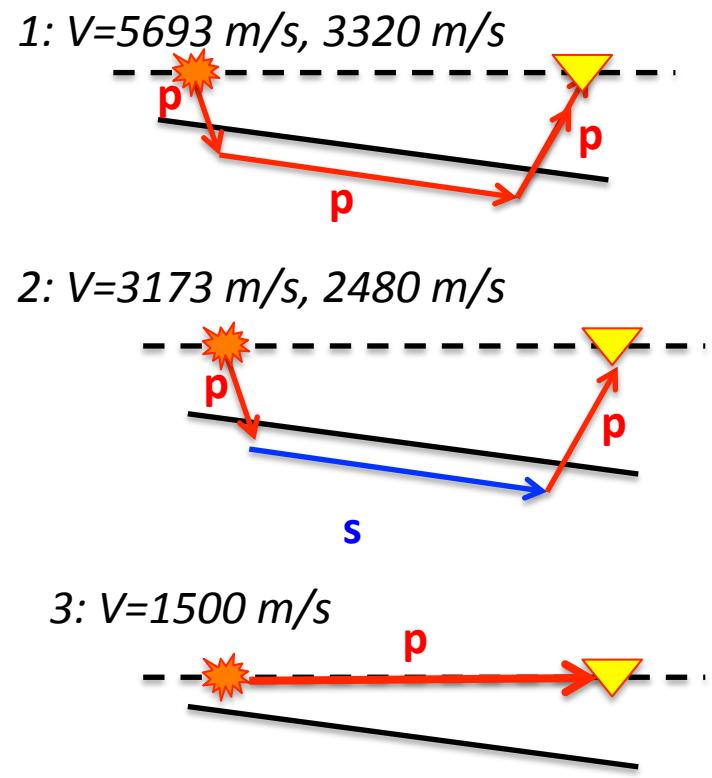
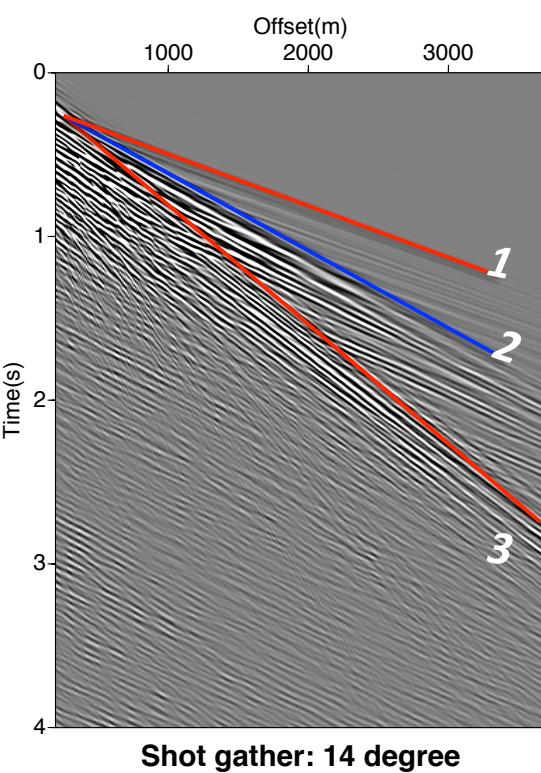
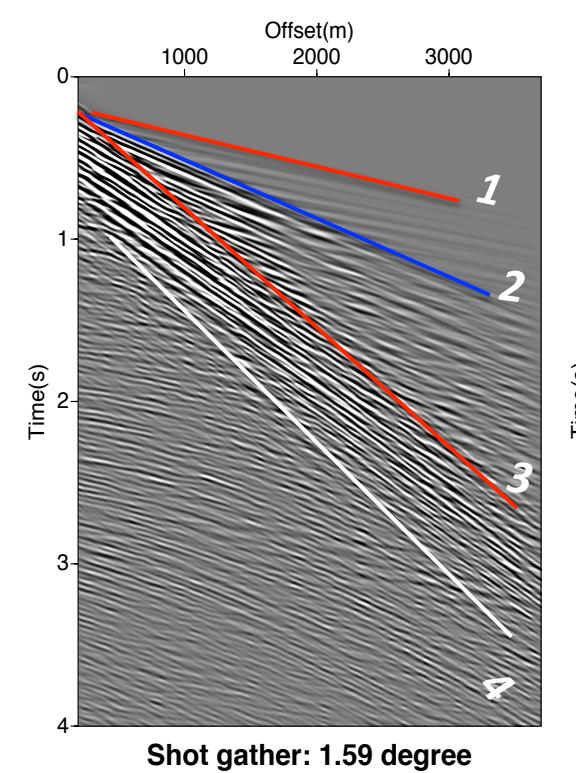
- Flat seafloor;
- Varying depth: 100 m, 10 m;



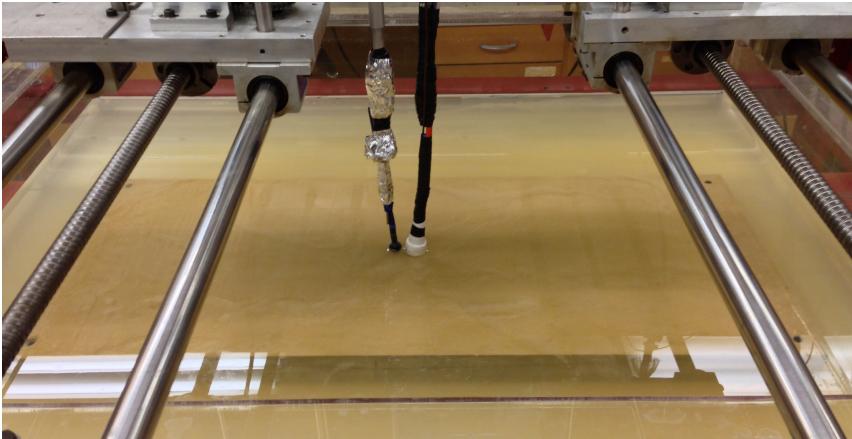
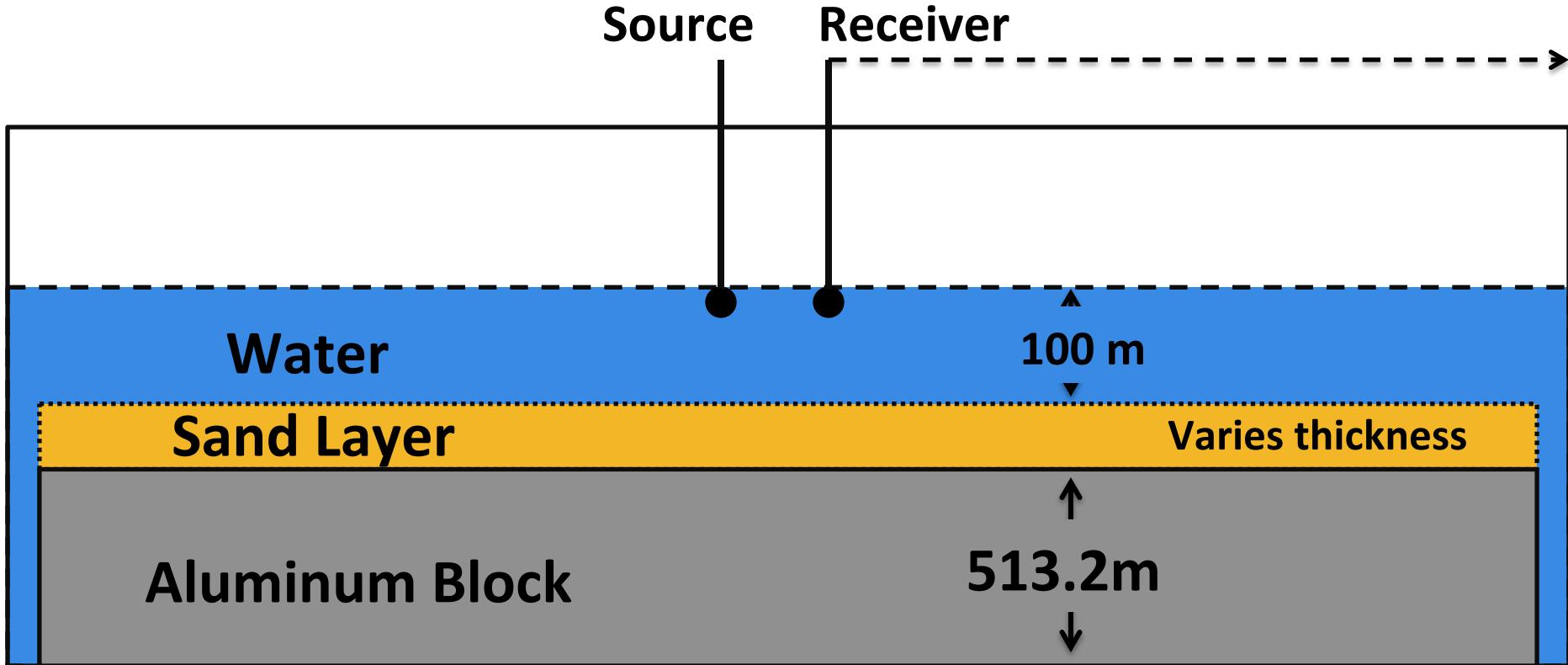
# Dipping seafloor

Dipping angles:  
 $1.59^\circ$  and  $14^\circ$

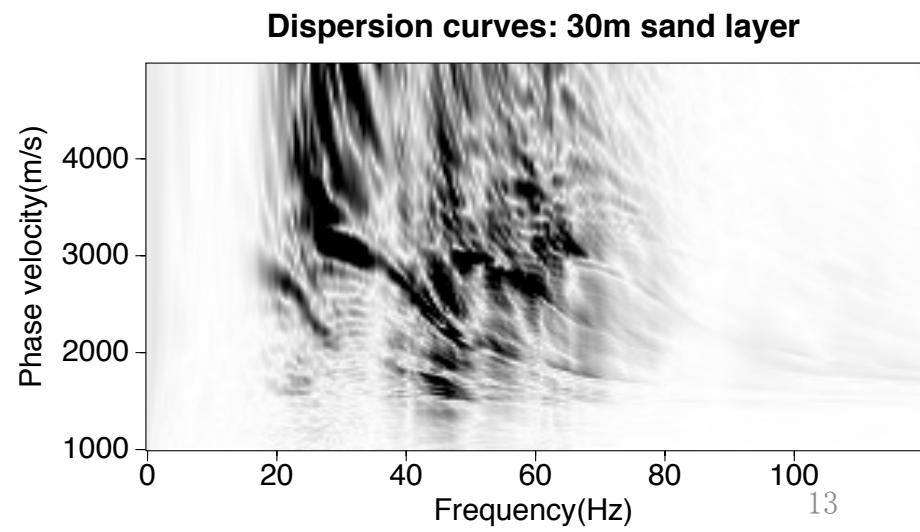
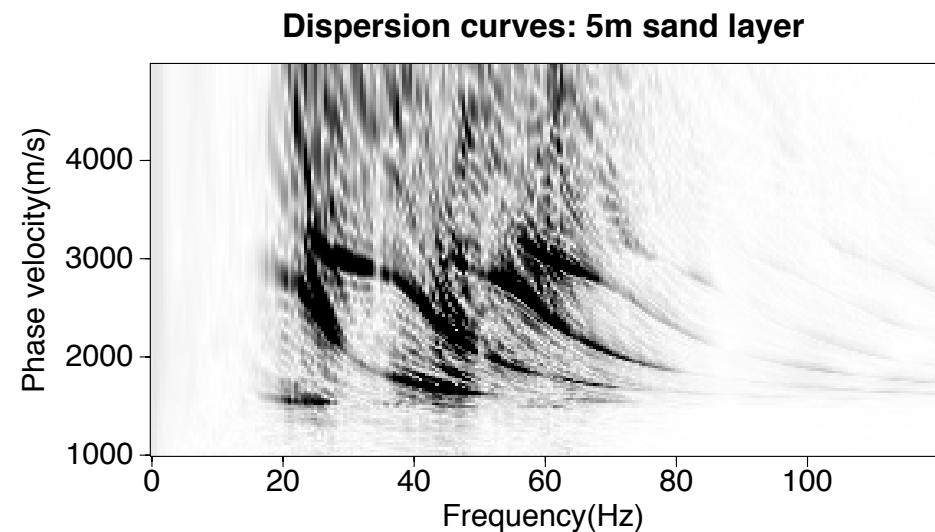
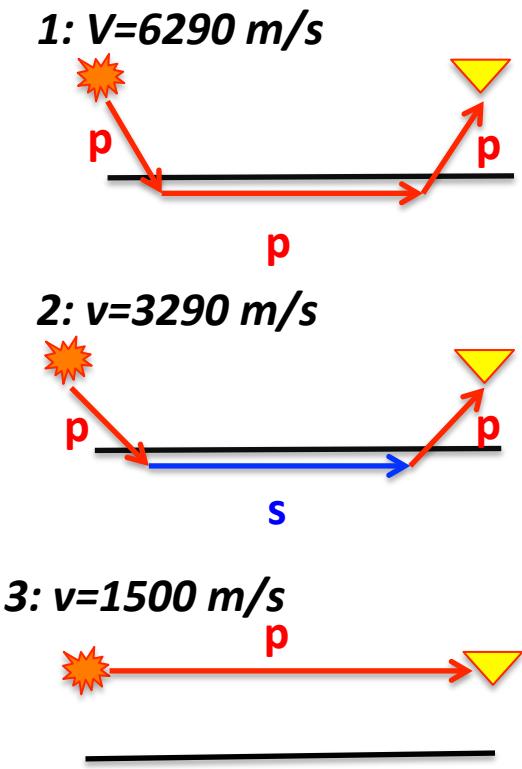
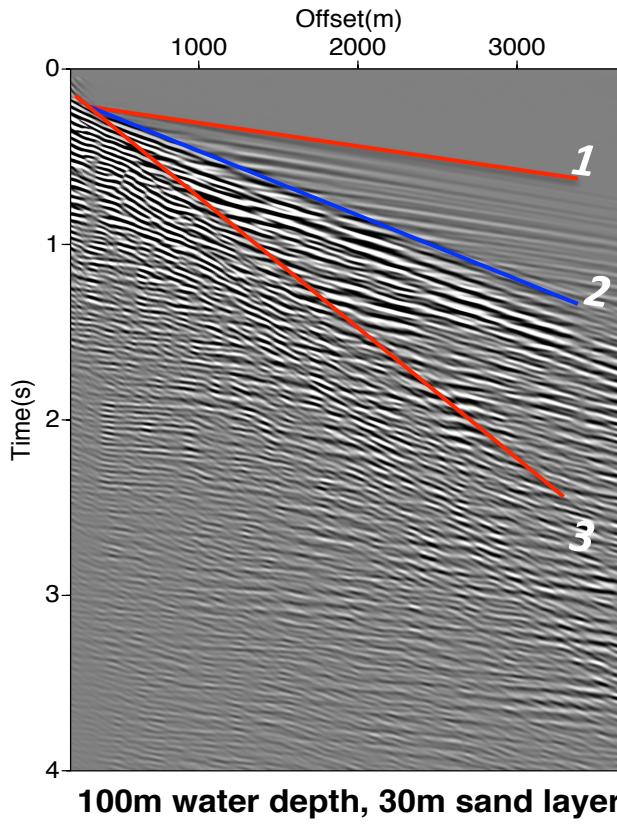
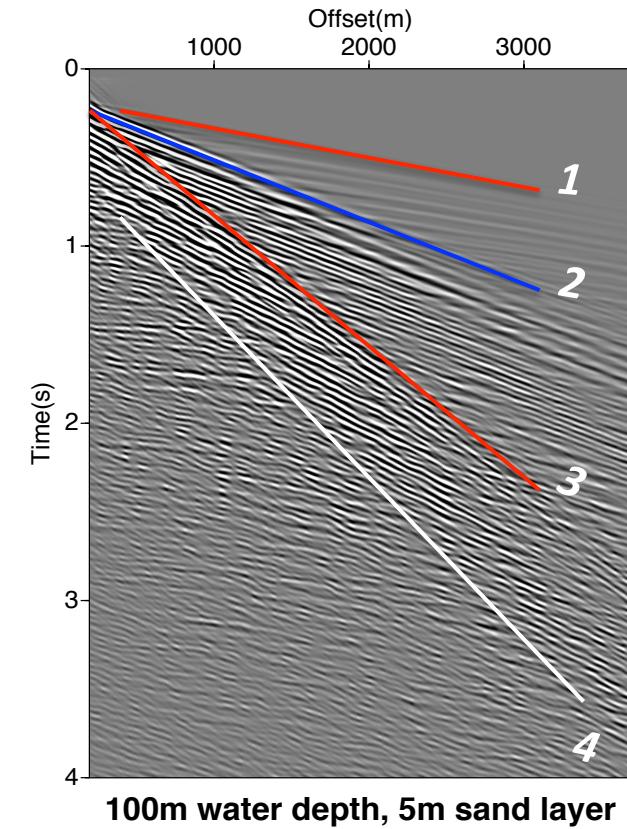




# Sandy interface cover

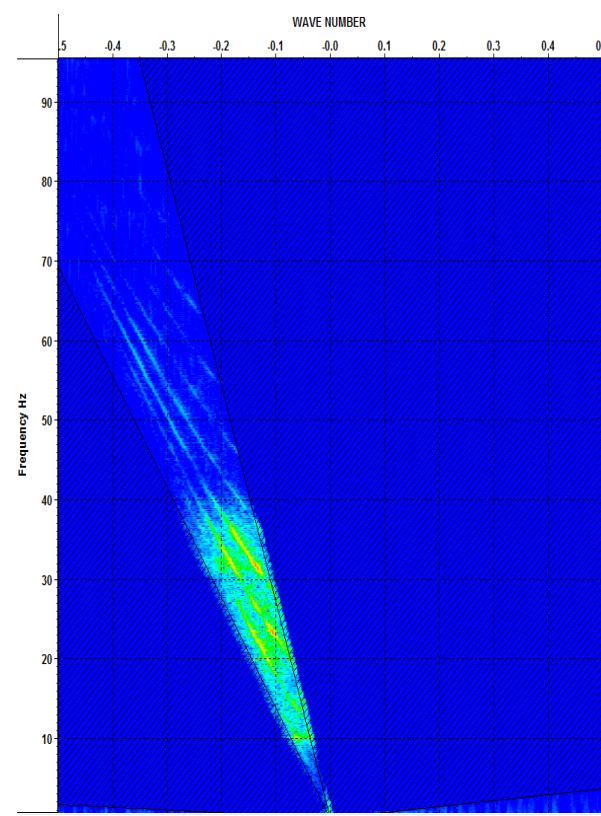
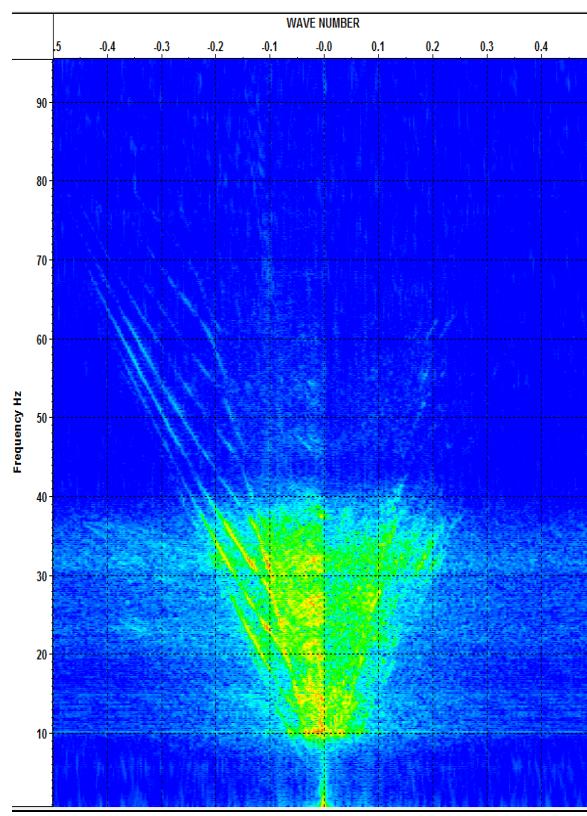
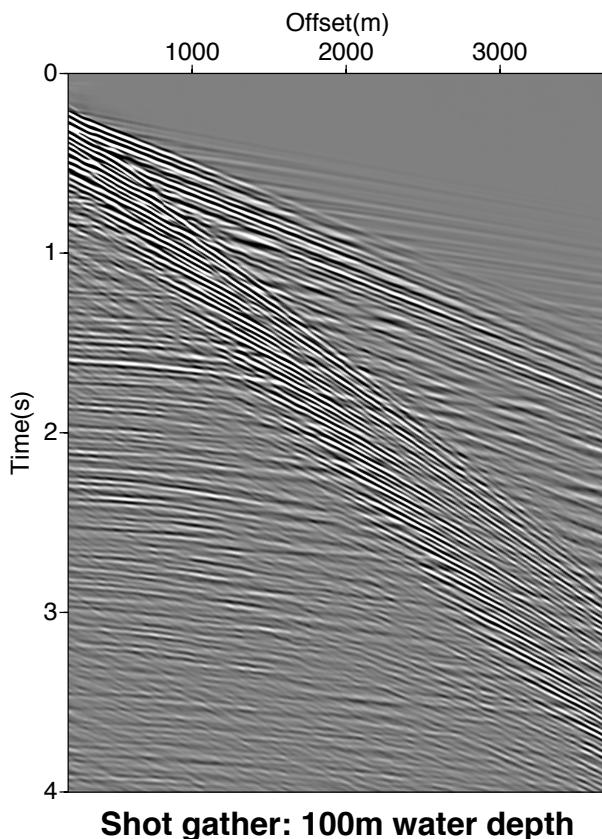


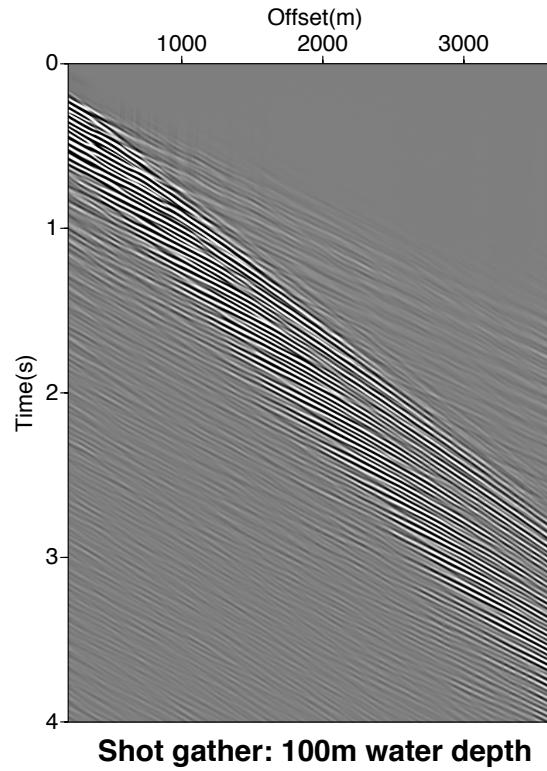
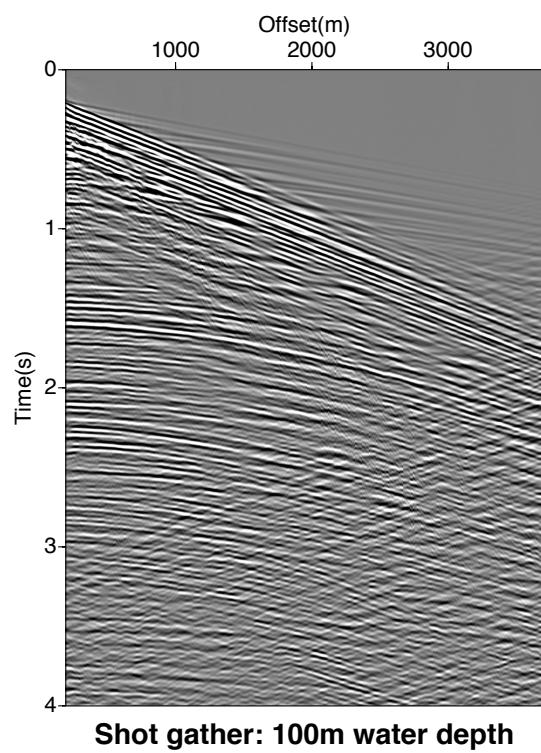
Sandy layer thicknesses:  
5 m and 30 m



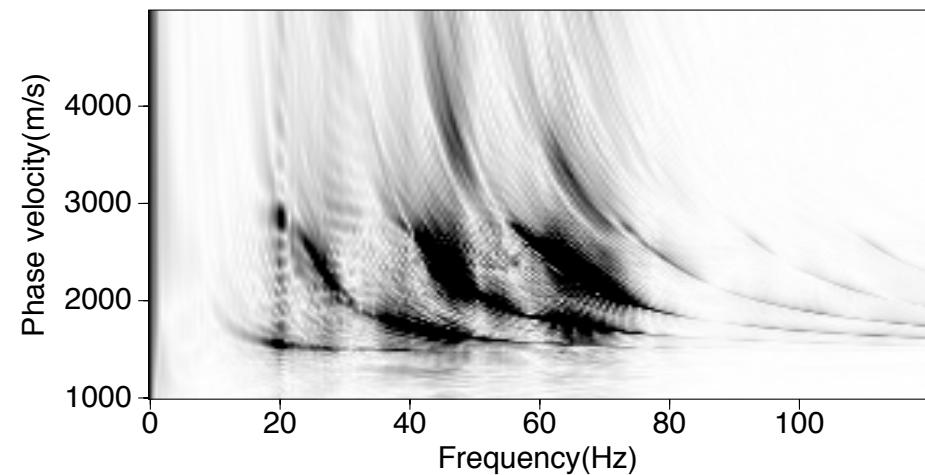
# Application

## Separate body waves and guided waves

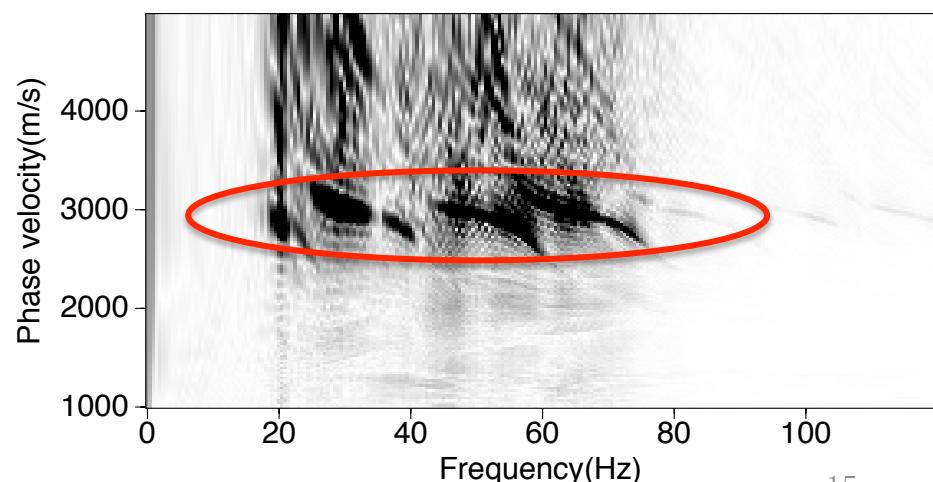


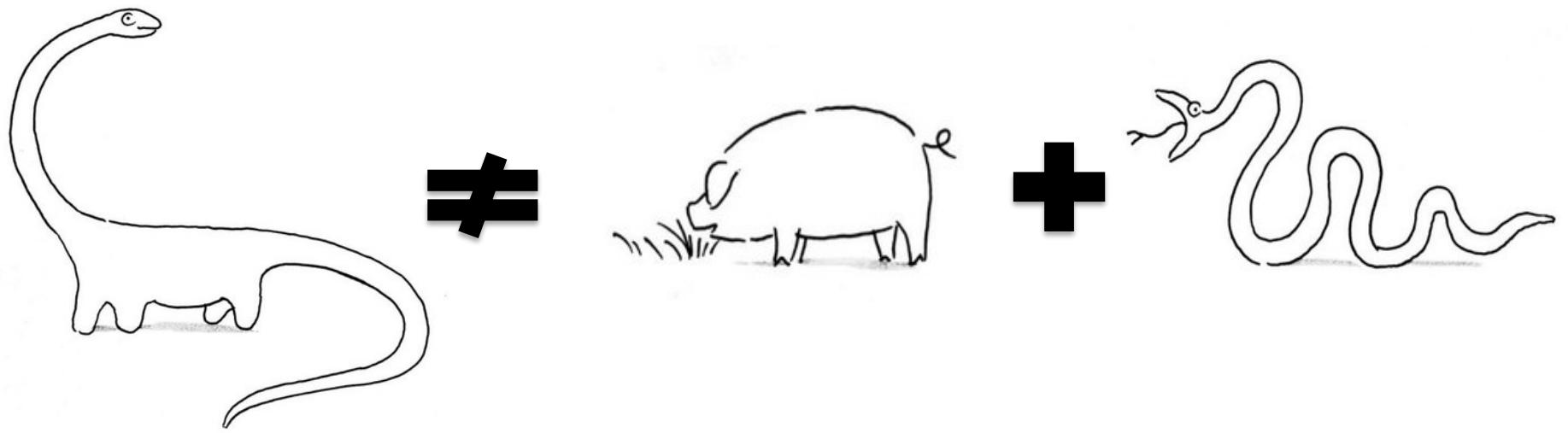


**Dispersion curves: 100m water depth**



**Dispersion curves: 100m water depth**



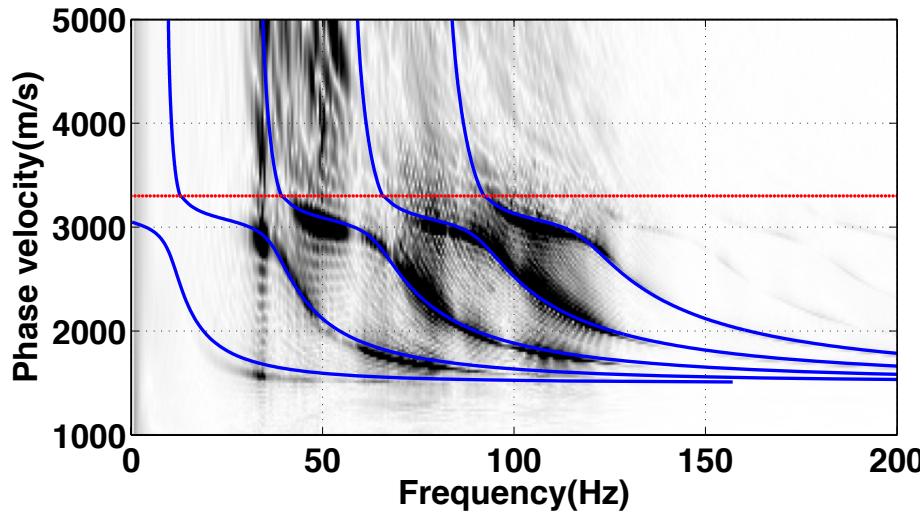


# Application

Transfer to  $v-f$  domain



Dispersion curves: 100m water depth



Shear wave velocity picking

Filter design



Shear-wave velocity profile building



Separate dispersive waves

# Conclusion

- The water depth dominates the number of normal modes;
- The properties of sedimentary layer dominate the energy distribution;
- The dipping angle of the seafloor dominates how modes couple together and bandwidth of the  $v-f$  spectrum.
- F-K filter cannot separate guided waves and body waves well. Filter design is necessary.

# Acknowledgements

- Dr. Robert Stewart
- Dr. Nikolay Dyaurov, Anoop William
- Dr. Lee Bell, Geokinetics;
- Soumyya Roy

Thank you